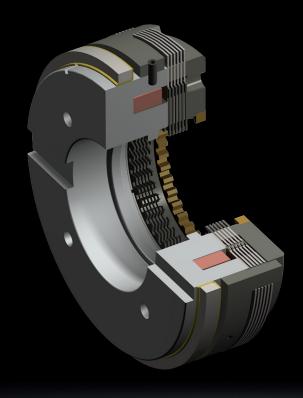




# Electromagnetic multiple-disc clutch Type 502



#### Electromagnetic multiple-disc clutch - Type 502

#### **Characteristics and features**

- suitable for torque transmission with increasing differential speed between the drive elements
- high torque transfer despite compact dimensions
- designs up to 1600 Nm possible
- particulary suitable for shifting operations with a high energy exchange
- negligible wear due to special friction lining
- only oil running
- maintenance free
- suitable for applications in harsh environments
- reduced shift speeds due to adapted control
- also available as electromagnetic multiple-disc brake













Mönninghoff power transmission represents an infinite variant diversity that is applied by all areas of modern mechanical engineering.

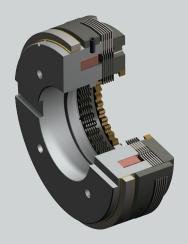
Our technologies are mostly designed to operate under extreme conditions. We offer high precision products for medical robotics, fail-proof security for aerospace technology or synchronization soultions for the packaging or printing industry.

We thus address customers who have the highest standards for their own machines or systems. To them, we can offer highly complex, application-specific solutions.

## Electromagnetic multiple-disc clutch - Type 502

#### Match code

Mönninghoff multiple-disc clutches are indicated by the following match code:



502 . A . B

A clutch size

**B** design

Other individual characteristics:

- voltage
- bore size with keyway

According to these characteristics, we design individual solutions concerning transmitted torque, engaging behavior or rotation speed.

Our engineers can assist with finding an application-specific clutch at any time. Together, we can develop individual and innovative solutions for extreme operating conditions.

## **Ordering example**

Mönninghoff electromagnetic multiple-disc clutch Type 502.21.1.1

Operating mode dry running Voltage 24 Vdc

Bore size d 30 mm H7, keyway acc to. DIN 6885/1



## Electromagnetic multiple-disc clutch - Type 502

#### Clutch size

The selection of the correct size of a Mönninghoff electromagnetic multiple-disc clutch is determined by the requiered torque as well as the shift work.

According to the required torque

$$M_{\rm S} \geq M_{\rm erf}$$

According to the shift work

$$E_h \leq Q_h$$

The clutch must transfer load and acceleration torque ( $M_L$ ;  $M_b$ ). The required safety is obtained by using a corresponding safety factor (K).

$$M_{erf} = (M_b \pm M_L) \cdot K$$

$$M_b = \frac{I \cdot \Delta n}{9,55 \cdot t} \quad [Nm]$$

$$Q_h = Q \cdot k_1 \cdot k_2 \quad [Nm]$$

$$E_h = \frac{I \cdot (\Delta n)^2 \cdot Z}{182.4} \quad [Nm]$$

If the load and acceleration torque cannot be determined, the required torque can be derived from the driving power, taking the required safety into cosideration.

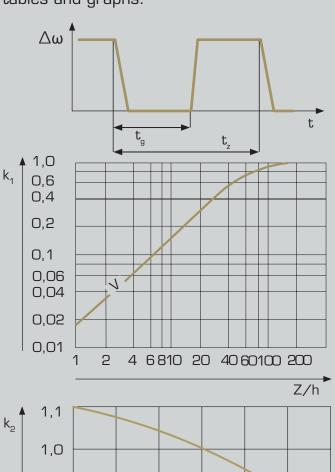
$$M_{erf} = 9550 \cdot \frac{P}{n} \cdot K$$
 [Nm]

$M_{erf}$	= required torque	Р	= driving power [kW]
$M_{\scriptscriptstyle b}$	= acceleration torque	K	= safety factor [1,2 to 4]
$M_{s}$	= shift torque	I	= moment of inertia [kgm²]
$M_{\scriptscriptstyle{L}}$	= output load torque	Z	= number of shift operations per hour
n	= speed of rotations [min <sup>-1</sup> ]	Q	= amount of heat
Δn	= differential speed of rotations [min <sup>-1</sup> ]	$E_{h}$	= shift energy per hour [Nm]
$k_1$	= correction factor	t	= acceleration time [sec]
$k_2$	= correction factor		based on $t_{\scriptscriptstyle 1}$
M <sub>L</sub> n Δn k <sub>1</sub>	<ul> <li>= output load torque</li> <li>= speed of rotations [min<sup>-1</sup>]</li> <li>= differential speed of rotations [min<sup>-1</sup>]</li> <li>= correction factor</li> </ul>	Q E <sub>h</sub>	<ul> <li>= number of shift operation per hour</li> <li>= amount of heat</li> <li>= shift energy per hour [Nm</li> <li>= acceleration time [sec]</li> </ul>

## Electromagnetic multiple-disc clutch - Type 502

#### **Determination of shift work**

The energy that is lost in the clutch depends on the shift curve and the shift frequency. The correction factors for the permissible shift work per hour  $Q_h$  can be derived from the tables and graphs.



Course of a shift cycle

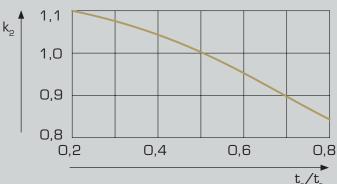
t<sub>a</sub> = time during which the clutch is closed

t, = total cycle time

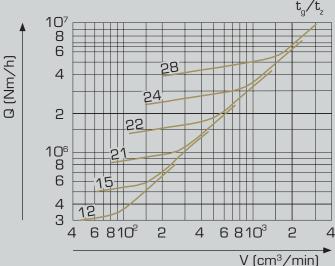
 $\Delta \omega$  = differential angular velocity

Correction factor  $k_1$  as a function of the shift frequency per hour

V valid for all sizes and types of clutches whose discs are surrounded by the field of force



Correction factor  $\rm k_{\rm 2}$  as function  $\rm t_{\rm g}/\rm t_{\rm z}$ 

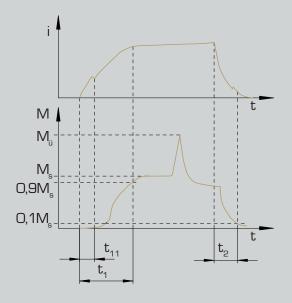


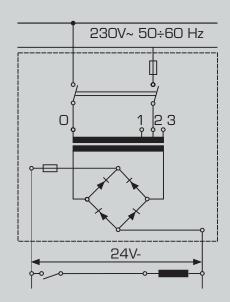
Amount of heat Q as function of the amount of cooling oil; valid for clutches whose discs are surrounded by the field of force

## Electromagnetic multiple-disc clutch - Type 502

#### **Switching**

Electromagnetic clutches are inductances. Engagement and disengagement are subject to the laws of induction, i. e. the induction current increases according to an e-function.





Shift speeds

Shift diagram: normal shifting

- ullet  $t_1$  and  $t_2$  can be electrically influenced by taking appropriate measures
- it is advisable to use direct current for shifting
- when determining the size, the engage time is considered to be approximately 30% of the total acceleration time, which normally results in additional safety

#### **Technical data**

Size			16	21	22	24	26	28	
shift speeds acc. to VDE 0580:2011-11	t <sub>1</sub>	[msec]	220/140	250/160	360/250	450/330	600/450	900/600	normal excitation (fast excitation
	t <sub>2</sub>		70/60	90/80	110/100	200/180	250/220	400/350s	3 times)

i = induction current

t<sub>1</sub> = engage time

 $M_{\ddot{\text{U}}}$  = torque to be transferred / static torque

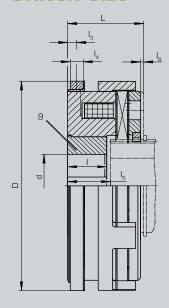
 $t_2$  = disengage time

 $M_s$  = torque to be shifted

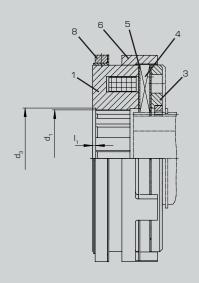
 $t_{11}$  = response delay

# Electromagnetic multiple-disc clutch - Type 502

## **Clutch** size



Type 1: with hub



Type 1: without hub

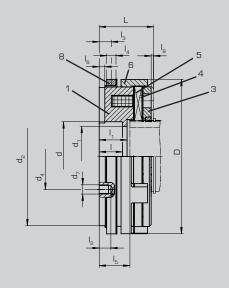
- Coilbody Armature Inner plate
- 1 Collbody
  3 Armature
  4 Inner plate
  5 Outer plate
  6 Drive ring
  8 Slip ring
  9 Hub Outer plate

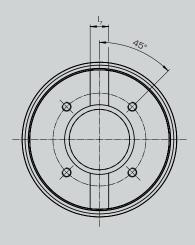
Size			12	15	21	22	24	28
torque		M <sub>s</sub> dyn [Nr	n] 25	60	120	250	480	960
max. speed		[min	3000	3000	2400	2000	2000	2000
input power		[V	V] 18	30	30	45	66	88
inertia	parts 1, 5, 6, 8, 9	[10 <sup>-3</sup> kgm	<sup>2</sup> ] 1,1	3,0	6,8	16,8	39	93
	parts 3, 4		0,18	0,5	1,45	4,8	11	34
weight		[k	gl 1,25	2,25	4	6,4	10,5	18
number of plates	inner plate		4	5	5	5	6	6
	outer plate		4	5	5	5	6	6
min. bore	keyway acc. to DIN 6885/1	d H7 [mr	15	20	25	30	35	50
max. bore	Reyway acc. to bit cood/ 1	1117	25	32	38	52	62	75
number of keyways in the hub			1	1	2 x 180	2 x 180	4 x 90	4 x 90
multikeyway	DIN 5462	d <sub>1</sub>	8 x 36	8 x 46	8 x 52	10 x 72	10 x 82	10 x 102
			8 x 40	8 x 50	8 x 58	10 x 78	10 x 88	10 x 108
dimensions		D [mr	n] 95	114	134	166	195	240
		d₁ H7	36	46	52	72	82	102
		d <sub>3</sub> H9	42	52	60	80	90	110
		L	36	45,5	52	58,5	68,5	77
		I -O,1	20	23	26	30	33,5	37
		I <sub>1</sub>	1,5	2	2	2,5	3	3
		$I_3$	5,5	6	7	7	7	8,5
		$I_4$	8	8	10	10	10	10
		I <sub>5</sub>	23	26	29	33	36,5	40
A		I <sub>8</sub>	1,2	1,8	2	2,5	3,5	5



## Electromagnetic multiple-disc clutch - Type 502

## Clutch size





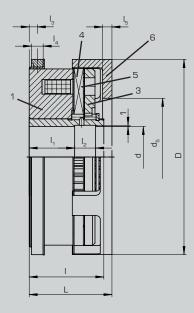
- 1 Coilbody
  3 Armature
  4 Inner plate
  5 Outer plate
  6 Drive ring
  8 Slipring

Type 3

Size				12	15	21	22	24	28
torque		M <sub>s</sub> dyn	[Nm]	25	60	120	250	480	960
max. speed			[min <sup>-1</sup> ]	3000	3000	2400	2000	2000	2000
input power			[W]	18	30	30	45	66	88
inertia	parts 1, 5, 6, 8	1	[10³kgm²]	1,5	3,7	7,23	19,3	40	95
	parts 3, 4			0,18	0,5	1,45	4,8	11	34
weight			[kg]	1,2	2	3,5	6,5	9,3	16,7
number of plates	inner plate			4	5	5	5	6	6
	outer plate			4	5	5	5	6	6
dimensions		D	[mm]	95	114	134	166	195	240
		d K6		42	55	68	75	90	110
		$d_1$		37	45	60	65	80	100
		$d_2$		85,5	95	120	150	178	218
		$d_{\scriptscriptstyle{4}}$		56	75	90	100	116	145
		d <sub>7</sub>		M6	M8	M8	M10	M10	M12
		L		38	49,5	55	58,5	69	80
		I +0,2		20	22	22	25	28	32
		l <sub>1</sub>		22	27	29	30	34	40
				5	8	8	10	12	18
		l <sub>3</sub>		7,5	11	11	13	13	14,5
		$I_4$		8	8	10	10	10	10
		l <sub>5</sub>		25	30	32	33	37	43
		I <sub>6</sub> +0,1		2,5	5	5	6	6	6
		I <sub>7</sub> H7		12	14	16	20	20	25
		l <sub>s</sub>		1,2	1,8	2	2,5	3,5	5

## Electromagnetic multiple-disc clutch - Type 502

## Clutch size



- 1 Coilbody 3 Armature 4 Inner plate 5 Outer plate 6 Drive ring

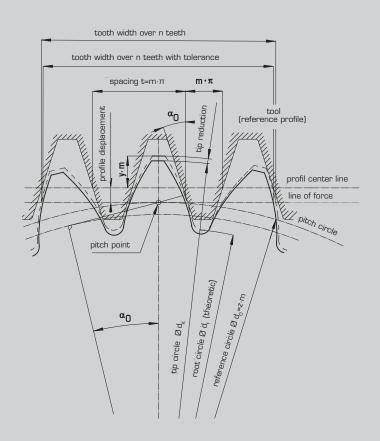
Type 4

Size			12	15	21	22	24	28
torque		M <sub>s</sub> dyn [N	lm] 25	60	120	250	480	960
		$\rm M_s$ stat	40	100	200	400	800	1600
max. speed		[m	n-1] 3000	3000	2400	2000	2000	2000
input power			<b>W]</b> 18	30	30	45	66	88
inertia	parts 1, 3, 4	[10 <sup>-3</sup> kg	m²] 1,2	3,2	7,4	20,5	48	117
	parts 5, 6		0,5	1,6	3	7	14,5	50
weight			<b>kg]</b> 1,5	2,6	4,5	7,8	13,7	26,5
number of plates	inner plates		5	6	6	6	7	7
	outer plates		4	5	5	5	6	6
min. bore	keyway acc. to DIN 6885/1	d H7 [n	nm] 15	20	25	30	35	50
max. bore			25	32	40	50	60	75
dimensions			n <b>m</b> ] 95	114	134	166	195	240
		d <sub>5</sub> H7	45	51	61	75	90	112
		L	46	55	61,5	71	85	90
		I -O, 1	41	49	56	64	76	80
		I <sub>1</sub>	31	29	32	39	43	42
		$I_2$	10	14	14	18	20	20
		l <sub>3</sub>	6	6	7	7	7	8,5
		$I_4$	8	8	10	10	10	10
		l <sub>5</sub>	5	6	6	8	9	10



## Electromagnetic multiple-disc clutch - Type 502

#### **Inner driver**



#### Gear specifications acc. to DIN 867

Index 1: design 1, 2 and 4 possesse 28 teeths

Index 2: design 3 possesses 31 teeths

the surface hardness of the driver is
 59 - 62 HRc

case depth can vary from 0,2 to 0,6 mm



z = number of teeth

m = module

 $d_{\cap}$  = reference diameter (= z·m)

d, = outside diameter

d<sub>f</sub> = root diameter

 $\alpha_{\cap}$  = pressure angle (= 20°)

Size			12	15	21	21	22	24	28
index					1	2			
number of teeth	Z		27	27	28	31	27	33	42
module	m		1,5	1,75	2	2	2,5	2,5	2,5
outside diameter	d <sub>k- 0,2</sub>	[mm]	43,3	50,5	60,5	66,4	73,2	88,2	110,0
root diameter	d <sub>f</sub>	[mm]	37,65	43,96	52,64	58,68	63,40	78,40	98,15
tooth width	Wn <sub>-0,06</sub>	[mm]	16,37	19,11	22,01	22,10	27,51	27,72	34,48
number of measuring teeth over "n" teeth			4	4	4	4	4	4	5
profile displacement	х	[mm]	+0,3	+0,31	+0,41	+0,42	+0,43	+0,43	-0,12
tooth length	zmin	[mm]	12	18,5	21,5	21,5	23,5	30	33,0

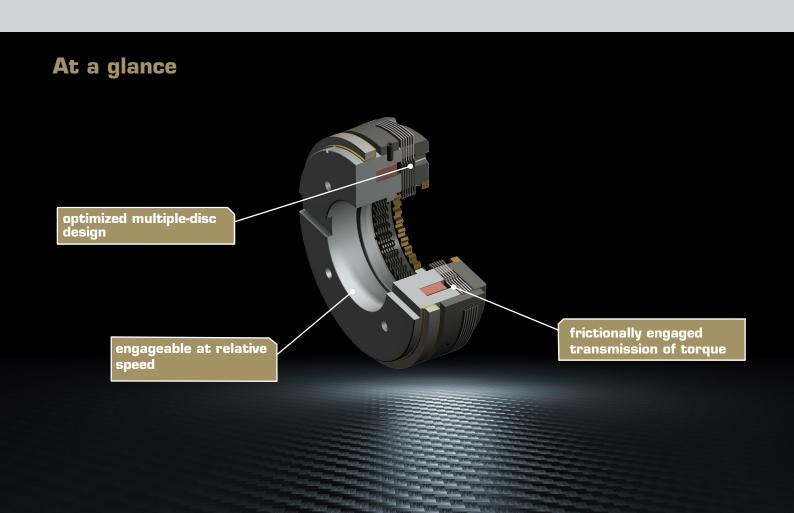
#### Electromagnetic multiple-disc clutch - Type 502

#### Voltage

- standard voltage is 24 Vdc dirrect current
- special voltages as a example 48 Vdc on request

#### **Technical characteristic**

- must run in oil
- the arrangement of the discs between the pole faces and the armature requires the discs to be made of a ferromagnetic material with good friction and wear properties, which are obtained by hardening and nitriding
- residual magentism resulting from the hardening process is eliminated by the special design of the discs
- the shape of the discs prevents the oil from building up when the temperature drops, thus avoiding shift delays
- clutches whose discs are surrounded by the field of force are paritculary suitable for shifting operations with a high energy exchange
- require no maintenance



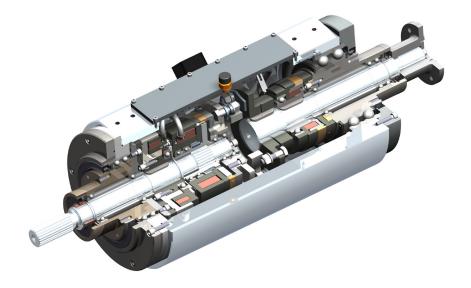
#### **System solutions**

#### You need more?

Mönninghoff clutches can be combined with a variety of many other power transmission elements. Such complex high-tech systems can solve any application-specific tasks and can fulfill any customer-specific wishes.



In many cases, a combination of different drive elements is needed to solve the applications particular problems and difficulties. Being not just supplier but technological partner to our customers, our extensive engineering is part of extraordinary and challenging power transmission projects.





#### **Driven by excellence**

#### Why Mönninghoff

- intensive dialog with our customers' engineers
- decades of experience and competence
- deep understanding for all areas of mechanical engineering
- highly modern and flexible machine park
- enthusiasm for quality
- flexibility, inventiveness and communication skills of our employees
- commitment to Germany and Bochum as industrial location



Helps you find a customer-specific power transmission solution for extraordinary circumstances.



For the competent processing and smooth handling of your orders and delivery dates.



**NSW LOCATION** 

Feels committed to protect and preserve the high value of your machine and to secure its availability.



